

Theorems
for
Free

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Deduce the following “Free Theorem”:

for all types X, Y ,

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for all lists $l: \text{List } X$,

$$M (\text{map } f l) = \text{map } f (M l).$$

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Without looking at the implementation of M .

Polymorphism

Ad-hoc Polymorphism

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$\left. \begin{array}{l} \text{add} : \text{Integer} \rightarrow \text{Integer} \rightarrow \text{Integer} \\ \text{add} : \text{Float} \rightarrow \text{Float} \rightarrow \text{Float} \end{array} \right\} \text{multiple implementations}$

implementation chosen at either compile-time or run-time

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Parametric Polymorphism

$\forall \alpha. \text{List } \alpha \rightarrow \text{List } \alpha \} \text{single implementation}$

single implementation works for all types

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such that $x_1 R y_1, x_2 R y_2, x_3 R y_3$

then:

$M l_X = [x'_1, \dots, x'_n], M l_Y = [y'_1, \dots, y'_n]$ and for all $i, x'_i R y'_i$

From Types to Relations

If A is a type with free variables $\alpha_1, \dots, \alpha_n$

and we have types X_1, \dots, X_n , and Y_1, \dots, Y_n

and relations $R_1 : X_1 \leftrightarrow Y_1, \dots, R_n : X_n \leftrightarrow Y_n$

then $\llbracket A \rrbracket : (A[X_1/\alpha_1, \dots, X_n/\alpha_n]) \leftarrow (A[Y_1/\alpha_1, \dots, Y_n/\alpha_n])$

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Definition

$$\begin{aligned}\llbracket \alpha_i \rrbracket &= R_i \\ \llbracket \forall \alpha. A \rrbracket &= \{(x, x') \mid \forall X, Y, R : X \leftrightarrow Y. x \llbracket A \rrbracket x'\} \\ \llbracket A \rightarrow B \rrbracket &= \{(f, g) \mid \forall (x, x') \in \llbracket A \rrbracket. (fx, gx') \in \llbracket B \rrbracket\} \\ \llbracket \text{List } A \rrbracket &= \{(l, l') \mid |l| = |l'| \text{ and for all } i, l_i \llbracket A \rrbracket l'_i\}\end{aligned}$$

Reynolds' Abstraction Theorem

If M has type A , then $M[A]M$.

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Caveats

Depends heavily on the language!

- general recursion* : (some) relations must be *admissible*
- effects* : (some) relations must be $\top\top$ -closed
- seq* : (some) relations must be *bottom-reflecting*
- typecase* : things get weird

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$M[\forall \alpha. \text{List } \alpha \rightarrow \text{List } \alpha]M$

Which means

For all types X, Y and relations $R : X \leftrightarrow Y$,

for all l_X and l_Y such that $l_X[\text{List } \alpha]l_Y$,

$(M l_X)[\text{List } \alpha](M l_Y)$

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$(M l_X) \llbracket \text{List } \alpha \rrbracket (M l_Y)$

Instantiating

Set $R = \{(x, y) \mid fx = y\}$

then $l_X \llbracket \text{List } \alpha \rrbracket l_Y \Leftrightarrow l_Y = \text{map } f l_X$

so for all $l, M(\text{map } f l) = \text{map } f(M l)$

Representing Datatypes

Representing Lists

$$\forall \alpha. \alpha \rightarrow (A \rightarrow \alpha \rightarrow \alpha) \rightarrow \alpha$$
$$\cong$$
$$\text{List}(A)$$

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Representing Syntax

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Terms of the untyped λ -calculus with no free type variables

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Terms of the untyped λ -calculus with no free type variables

$$\lambda \text{lam}. \lambda \text{app}. \text{lam } (\lambda x. \text{lam } (\lambda y. \text{app } x y)) \approx \lambda xy. xy$$

Beyond Type Quantification

For any function *area* with the type:

$area : \forall B:GL_2, t:T_2.$

$vec\langle B, t \rangle \rightarrow vec\langle B, t \rangle \rightarrow vec\langle B, t \rangle \rightarrow real\langle |\det B| \rangle$

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Deduce translation invariance:

$\forall \vec{t}, \vec{v}_1, \vec{v}_2, \vec{v}_3. area (v_1 + t) (v_2 + t) (v_3 + t) = area v_1 v_2 v_3$

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Deduce orthogonal transformation invariance:

$$\forall O, \vec{v}_1, \vec{v}_2, \vec{v}_3. \text{area} (Ov_1) (Ov_2) (Ov_3) = \text{area } v_1 v_2 v_3$$

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Deduce scaling variance:

$$\forall s, \vec{v}_1, \vec{v}_2, \vec{v}_3. \text{area} (s \cdot v_1) (s \cdot v_2) (s \cdot v_3) = s^2 \cdot \text{area } v_1 v_2 v_3$$

Types to Relations

$$\begin{aligned} [\forall B : \mathbf{GL}_2.A] &= \{(x, x') \mid \forall B : \mathbf{GL}_2. x[A]x'\} \\ [\forall t : \mathbf{T}_2.A] &= \{(x, x') \mid \forall t : \mathbf{T}_2. x[A]x'\} \\ [\forall s : \mathbf{GL}_1.A] &= \{(x, x') \mid \forall s : \mathbf{GL}_1. x[A]x'\} \\ [\mathbf{vec}\langle B, t \rangle] &= \{(\vec{v}_1, \vec{v}_2) \mid \vec{v}_2 = B\vec{v}_1 + t\} \\ [\mathbf{real}\langle s \rangle] &= \{(x_1, x_2) \mid x_2 = sx_1\} \end{aligned}$$

area : $\forall B:GL_2, t:T_2.$

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Symmetry as a Guide:

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Symmetry as a Guide:

We have $p_1 : vec\langle B, t \rangle, p_2 : vec\langle B, t \rangle, p_3 : vec\langle B, t \rangle$

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select one to be the “origin”:

$$(p_2 - p_1) : \text{vec}\langle B, 0 \rangle \text{ and } (p_3 - p_1) : \text{vec}\langle B, 0 \rangle$$

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remove rotational symmetry and get area of parallelogram:

$$(p_2 - p_1) \times (p_3 - p_1) : real\langle \det B \rangle$$

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The Message

Polymorphism means Uniformity

If a type has a \forall , then implementations are uniform under change:

$\forall \alpha.$: uniform under change of data representation

$\forall B : \text{GL}_2.$: uniform under change of basis

$\forall t : \text{T}_2.$: uniform under change of origin

$\forall s : \text{GL}_1.$: uniform under change of scale

Uniformity allows one to deduce “free theorems”

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What other sorts of uniformity are useful?